

Original declaration of incorporation with manual for

ARIS Actuator ExTensor

Actuator for potentially explosive atmospheres of zone 1





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1. Identification

This manual is valid for:

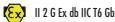
Description: Electrical actuator for potentially explosive atmospheres ATEX / IECEx

Type: ExTensor (and add-ons/options)

Further details see chapter 1.2 nameplate / labeling

1.1 Approvals / Labeling

ATEX (Gas)



ATEX (Dust)



II 2 D Ex tb IIIC T80°C Db

IECEx



IECEx IBE 22.0020X

EU type examination certificate no. IBExU22ATEX1066 X Type of construction: Flameproof enclosure

1.2 Nameplate / Labeling

The actuators hold two nameplates. They are located on the outside of the actuator.

Plate 1: Metal nameplate with all details for ATEX / IECEx: plate 2: Label with actuator specific data

Metal nameplate ATEX / IECEx details



Description:

Actuator type
Manufacturer information
Ignition protection type
IECEx number
Number of licensing office
Power rating
IP protection class
Ambient temperature

Label with actuator specific data



Description:

Actuator type
Serial number (YYWW=Construction year+week)
Power rating
IP protection class / Ambient temperature
Equipment features / Options

(Plate and label examplary)

1.3 Guidelines and standards

ARIS actuators are partly completed machinery according to directive 2006/42/EC. This is certified by the EC declaration of incorporation (see page xxx).

The present electrical actuators for potentially explosive zones meet the essential safety and health protection requirements according to Appendix II of the ATEX Directive 2014/34/EU by complying with

EN IEC 60079-0:2018 / IEC 60079-0:2017 Edition 7.0 and

EN 60079-1:2014 / IEC 60079-1:2014 Edition 7.0 and EN 60079-31:2014

Further applicable EC directives: EMC Directive 2014/108/EC DIN EN 61000-3-2

DIN EN 61000-3-3 DIN EN 61000-6-2 DIN EN 61000-6-3 DIN EN 61000-6-4 DIN EN 55011

Applied harmonized standards: MachDir 2006/42/EC DIN EN 61010-1:2011-07

DIN EN 12100:2011-03

Protection class by enclosure (IP-Code) Protection class testing DIN EN 60529 (IP65/IP67)



EMC considerations of the overall system and system perturbations and their combating have to be treated by the system manufacturer or system operator. The wiring of the actuator should be carried out in accordance with FN IFC 60079-14.

2. Safety information

2.1 Warnings

Installation and initial operation only by certified experts according to this manual. Observe the significance of the following symbol and note explanations. They are subdevided in security levels and classified according to ISO 3864-2.

▲ DANGER	DANGER indicates a hazard with a high risk degree, which, if not avoided, causes death or heavy injuries.
WARNING	WARNING indicates a hazard with a medium risk degree, which, if not avoided, can cause death or heavy injuries.
ACAUTION	CAUTION indicates a hazard with a low risk degree, which, if not avoided, can cause slight or moderate injuries.
() ADVICE	Indicates general advice, useful hints and work recommendations, which don't have influence on the safety and health of the staff.

2.2 General safety advice



- This manual has to be kept at the operating site at any time.
- Read the manual carefully prior to installation and initial operation.



While operating electronic devices certain parts are obligatory under hazardous voltage.

The manufacturer reserves the right to make technical changes and improvements at any time.

3. Technical specification

3.1 Functions and application areas (Intended use)

ARIS actuators of the ExTensor series are designed exclusively for industrial use in potentially explosive areas according to their labeling. They are used to actuate control and shut-off devices (flaps, valves, taps, sliders, dosing pumps, etc.).

ARIS actuators may not be used for

- in continuous underwater use (observe protection class)
- in hazardous areas of zones 0 and 20
- in Group I hazardous areas (mining)
- in radiation-exposed areas in nuclear plants
- at temperatures below -20 °C or above +60 °C
- underground
- near open fires

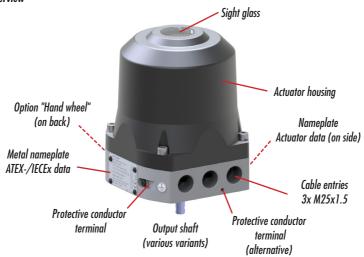
ARIS Stellantriebe GmbH assumes no liability for any production errors and the resulting damage or consequential damage after the drive has been checked, installed and declared functional.

In particular, ARIS Stellantriebe GmbH assumes no liability for any production errors and the resulting damage or consequential damage in the event of improper use of the drive, if the drive has not been adequately tested within an overall system, or if errors are found during an initial or further test and the drive is not was immediately taken out of service.

3.1.1 Special conditions for safe use of the actuator in hazardous areas (Acc. point 17, EC type examination certificate)

- The actuator can be used in an extended ambient temperature range from -20 °C to +60 °C.
- Repairs to the flameproof gaps may only be carried out in accordance with the manufacturer's design specifications. Repairs
 according to the values in Tables 2 and 3 of EN 60079-1 are not permitted.
- Only the screw pluas specified by the manufacturer (strenath class at least A2-70 according to ISO 4762) may be used.
- The cable and line entries used must be suitable for a maximum operating temperature of at least 80 °C. All openings that
 are not required for the introduction of cables and lines must be permanently closed with suitable sealing elements that have
 been confirmed for explosion protection according to EN 60079-1 for group IIC or according to EN 60079-31 for group IIIC.

3.1.2 Overview



3.2 Housing entries (tapped holes)

3.2.1 Cable and wire entries

Features ARIS ExTensor 3x M25x1.5 tapped holes

When delivered, the actuators are provided with a transport protection (protective sticker), which covers the threaded holes of the cable and line entries. This must be removed and replaced with suitable, approved entries or plugs. The entries/blind plugs used must correspond to the ignition protection types of the drive. In addition, these must meet the IP protection class - at least IP65 and IP67.





DANGER! Operation with the sticker or parts thereof is not permitted.

Non-compliance can lead to serious accidents and property damage - The ATEX/IECEx approval of the device becomes void in the event of non-compliance or misuse.

Only suitable cable and line entries and blind plugs certified according to the ATEX/IECEx protection class may be used for the introduction of cables (lines) - the diameters must correspond to the cables used.

Unused housing entries (threaded holes) which are intended for the use of cable and line entries must be sealed with suitable blind plugs certified according to the ATEX/IECEx protection class. When selecting the correct cable and line entry, EN IEC 60079-14 must also be observed. The cable and line entries as well as blind plugs must be suitable for an operating temperature of at least +80°C.



DANGER! On the back of the drive, there is a blind plug to close the handwheel option for equipment variants without a handwheel. This may not be removed or altered. See also Chapter 6 - Handwheel section.

Another transport protection sticker is located on top of the drive hood to protect the sight glass during transport / storage. This must also be removed prior to commissioning. Operation with the sticker or parts thereof is not permitted. Non-compliance can lead to serious accidents and damage to property - The ATEX/IECEx approval of the device becomes void in the event of non-compliance or misuse.

Suitable products (cable entries, blind plugs) are available as accessories from ARIS, tailored to the ATEX/IECEx products. If required, these are loosely enclosed with the drive. The delivery is always unassembled.

Please note the correct assembly. The cable entries used must always be designed for the connecting cables and correspond to the cable diameters.

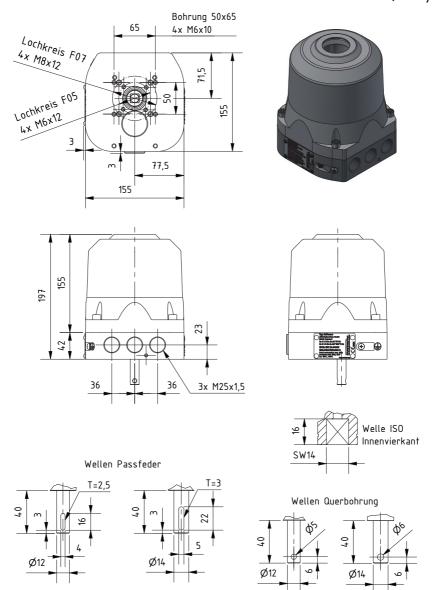
3.3 Performance data

Voltage supply AC	85265 V AC (50/60 Hz)	End position cutoff	Digital
Voltage supply DC	24 V DC (±10%)	Position feedback	Digital, contactless
Max. power consumption	60 VA	Connection	Cable/wire entry: 3x M25x1.5
Torque	5 Nm500 Nm	Ambient temperature	-20° C+60° C
Actuating time	1s/90°150s/90°	IP protection class	IP65/IP67
Motor type	BLDC		

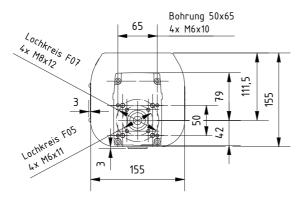


ARIS actuators type ExTensor correspond in their basic form (primary version) up to 40Nm torque - without gear extensions, the EU type examination certificate number IBEXU22A-TEX1066 X. - see appendix of these operating instructions. Variants with torques of 50 ... 500Nm (secondary versions) correspond to the primary version, but are supplemented by an externally mounted gear extension (planetary gear stage).

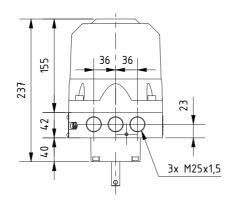
FxTensor 7

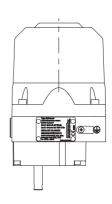


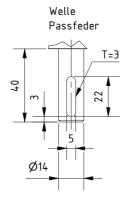
ExTensor Model "M" (Secondary model)

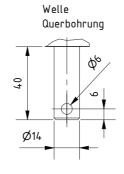


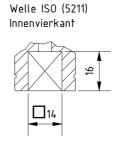




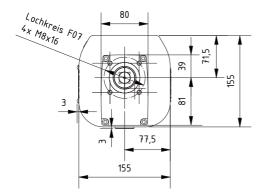




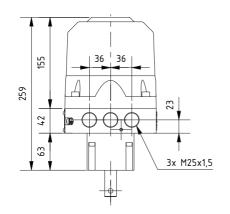


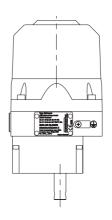


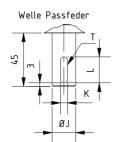
ExTensor Model"L" (Secondary model)

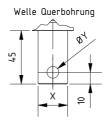












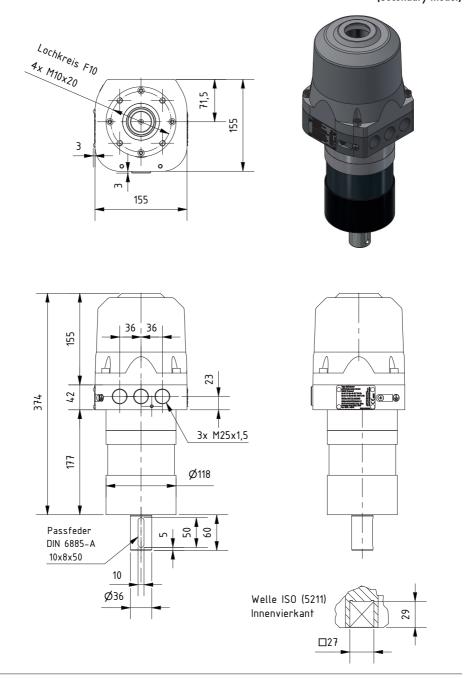
ISO-Welle Vierkantmaße					
Drehmoment Maß A					
17	21				
22	24				
	Maß A				

Welle Querbohrung					
Drehmoment	Maß ØX	Maß ØY			
80-150	20	8			
150-180	25	10			

Welle ISO (5211) Innenvierkant	m d	_
	_ A	
	-	

Wellen Passfeder				
Drehmoment Maß ØJ		Maß K	Maß L	Maß T
80-150 20		6 P9	22	3,5
150-180	25	8 P9	32	4

ExTensor Model "XL" (Secondary model)



3.4.1 Weights

ExTensor "S"	6.5 kg
ExTensor "M"	7.5 kg
ExTensor "L"	8.5 kg
ExTensor "XL"	15.5 kg

Weights are approximate and may vary slightly depending on the equipment variant.

4. Actuator setup for utilization

4.1 Transport, (temporary) storage and downtimes

Use the factory packaging for transport to the installation point.
Replace a damaged original packaging by a new solid packaging.

- Actuator with attached valve; only attach lifting agar to the valve and NOT to the actuator
- ARIS actuators must not be used as a climbing or supporting aid.
- ARIS actuators must not be operated in unsecured lifting mode without additional applications
- Storage in well-ventilated and dry rooms
- Protection against possible soil moisture (shelf storage)
- For longer storage times, moisture-absorbing agents should be placed in the drive
- The drives must be protected from dust and dirt
- Actions must be taken to avoid the formation of condensation (e.g. in the event of temperature fluctuations)

4.2 Packaging

ARIS drives are protected by special cardboard packaging for transport from the factory. Unpacking in the Ex area is not permitted as the materials could become electrostatically charged.

4.3 Safe disposal of packaging

Additionally necessary packaging is made by easily separable packaging materials and can be recycled individually:

- Wood
- Cardboard
- Paper
- Plastics

4.4 Installation and mounting

Installation, electrical connection, commissioning, operation and maintenance may only be carried out by trained specialist personnel who have been authorized by the system operator or system manufacturer.

Personnel requirements: National requirements, EN IEC 60079-14, EN IEC 60079-17, EN IEC 60079-19.

Before commissioning or working on this actuator, the personnel must have read and understood these instructions and also know and observe the applicable rules for occupational safety. Work in hazardous areas is subject to special conditions that must be observed. The plant manufacturer/operator is responsible for compliance and monitoring.

Prior to initial operation

- inspect drive for damage prior to installation
- the screw-in depth of the mounting screws must not be exceeded according to the information in the drawings
- before commissioning, check the tightness of the cable entries and blind plugs
- tighten the hood screws evenly (torque 12 Nm, also note the notes under point 5.1.1)
- protect the drive from the effects of the weather (e.g. with a protective roof)
- do not expose the drive to hard shocks (e.g. by dropping it);no ropes, hooks, etc. attach directly to the drive
- permanent overloading and blocking of the drive leads to damage to the drive
- only use original ARIS spare parts

Consider prior to attachment of couplings:

- Do not turn actuator shafts by force;
- actuator and valve shafts must run centric.



No additional holes may be drilled into the drive housing and the hood.

Any modifications to the actuator are strictly prohibited and will result in the loss of the ATEX/IECEx protection approval.

5. Initial operation



Work on open live drives, e.g. setting the end positions, may only be carried out if the occurrence of an explosive atmosphere can be ruled out for the period of work.

The actuator without the drive cover may only be operated for a short period of time for essential adjustment and commissioning processes.

Dangerous voltage: Electric shock possible!

- The drive may only be commissioned by qualified personnel!
- De-energize before opening the actuator.
- For electrical installation and commissioning, the applicable regulations have to be observed.

5.1 Opening the actuator



Do not disconnect under voltage!



Before removing the drive cover, the drive must be switched off from the power supply.

Installation and commissioning only by qualified specialists in accordance with the operating instructions.

After loosening and removing the cover screws, carefully lift the drive cover off the lower part of the housing. Do not tilt or wobble. This can lead to irreparable damage to the flameproof gap.

Only the screws installed on the drive may be used to mount the cover. If lost, screws of the same standard, dimensions and strength must be used.

Screw type: ISO4762 - M8x40 - A2-70

The drive cover is screwed to the lower part of the housing with 4 screws (M8x40). The drive cover and housing base are assembled with each other via a narrow, cylindrical fit to form the "flash-proof gap".

Care must therefore be taken when lifting the drive cover so that the components do not tilt.



When the cover hood is lifted, a vacuum can develop in the drive, which makes it difficult to lift the hood. This can be avoided by loosening a cable/line entry or blind plug so that air can flow through it.

DANGER! The lead-in must be professionally closed again before commissioning or for further storage.

Danger! Pressure proof encapsulation

To create the type of protection, flameproof gaps with narrow cylindrical fits are installed.

Gap surfaces must not be damaged. Damaged surfaces must not be machined or repaired in any other way - contact ARIS Service. Cover and housing parts must be handled with care.

Avoid tilting the components during assembly.

5.1.1 Closing the actuator

After the adjustments have been made, the drive cover must be reassembled.

Note the following points:

- The cleavage surfaces must be clean and free from contamination or damage
- The sealing surfaces must be clean and free from contamination or damage
- Check the seat of the seal (O-ring) on the lower part of the housing and make sure that it is undamaged and free of dirt
- If necessary, apply an anti-corrosion agent (Vaseline (petrolatum) or soap-thickened mineral oil) to the cylinder surfaces of the aan
- Put the drive cover back on without tilting it

Note the mounting orientation based on the flange geometry. When the hood is put on, overpressure can occur inside the drive, which means that the hood can only be pushed open slowly. Proceed slowly and carefully so that the air can escape. This can be avoided by loosening a cable/line entry or blind plug so that air can escape and the overpressure can be reduced.



The lead-in must be professionally closed again before commissioning or for further storage.

Tighten the screws step by step in a cross pattern, observe the tightening torque.

Tightening torque cover screws: M8x40 A2-70 = 12Nm

5.2 Electrical connection

The electrical connection may only be carried out by qualified electricians.



Dangerous voltage: Electric shock possible!

- The drive may only be commissioned by qualified personnel (electricians)!
- De-energize before opening the actuator.
 - The applicable regulations must be observed during electrical installation and commissioning.



Danger! Observe the regulations applicable to the hazardous area for handling electrical components in your operating environment.

To open the drive cover, proceed as described under 5.1.

The connection diagram in the drive is binding for the electrical connection. Note the voltage type!

Grounding

The drive must be provided with a protective conductor connection / grounding both inside and outside. The connection threads / positions are marked with the earth symbol

Outer PA connection at least 4 mm².

Before switching on for the first time, check:

- Is the drive externally undamaged?
- Is the mechanical attachment O.K.?
- Has the electrical connection been made correctly?
- Check whether the type of current, mains voltage and frequency match the motor data (see rating plates on the hood and in the drive).
- Use cable glands suitable for the connecting cable.
- Be sure to observe the wiring diagram glued to the hood.
- For extra-low voltages (e.g. potentiometers), separate, possibly shielded cables should be used.

Temperature monitor

To protect against increased temperatures, the actuator is equipped with a manually resettable bimetallic temperature monitor on the inside. This is connected in front of the operating voltage supply.

At increased temperatures > +85°C in the drive, the temperature monitor switches off the supply voltage and thus the drive. This serves to comply with the type of protection, the temperature class and the fulfillment of the ATEX/IECEx standards.

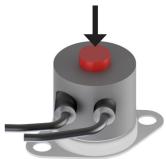
After a cooling phase of approx. 30 minutes and a temperature reduction of at least 10K, the temperature monitor can be reset manually by pressing the actuating button (red).

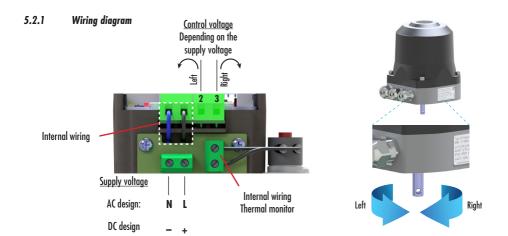
In doing so, observe the procedure and instructions for opening and connecting the drive in these operating instructions. De-energize the drive before opening.

Make sure that there is no explosive atmosphere in the area when working on the drive.

Also, before performing a reset, make sure that the causes of the elevated temperature have been eliminated.







Connection 85...265 V AC

N	Neutral conductor

L Phase / Supply 85 ... 265 V AC

2 Control connection > left-turning (CCW)

3 Control connection > right-turning (CW)

Ground wire inside of the housing.

Connection 24 V DC

— GND

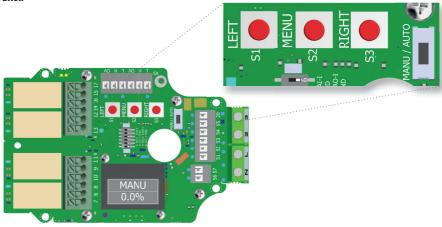
+ Connection 19.2...28.8 V DC

2 Control connection > left-turning (CCW)

3 Control connection > right-turning (CW)

6. Actuator operation without modules (Standard)

6.1 Operation



The Tensor² is operated via 3 buttons and a slide switch, located above the actuator's display. The OLED display makes setting up the actuator easier by showing text such as letters, numbers and signs.

Navigate between different menu items by using the buttons LEFT [L] & RIGHT [R].

6.1.1 Buttons and switches

The buttons (1) are indicated with LEFT [L]
MENU [M]
RIGHT [R]

The functionality of the buttons is explained in section "Operating modes".

6.1.2 Operating modes

The different operating modes of the actuator can be selected via the slide switch resp. the MENU button. The actual operating mode is shown on the display.



Automatic operation (AUTO mode, switch position "AUTO"):

The actuator runs with an external signal, which is present depending on the setting on the terminal clamps, the signal clamps or CAN clamps. The onboard buttons are without function.

Manual mode (MANU mode, switch position "MANU"):

The actuator can run left and right by using the buttons "L" & "R", if the actuator is not in setup mode. Change to setup mode by pressing the MENU button longer than >1s.

Setup mode (Switch position "MANU"):

Different actuator parameters can be set up and adjusted.

Start setup mode:

- 1. Slide switch to position MANU"
- 2. Press button MENU longer than >1s

Setup mode is turned on and the first menu item "MAIN MENU" is displayed.

Within the setup menu navigate between different menu items and adjustments by pressing the buttons "L" & "R".

Confirm any entry by pressing the MENU button (press < 0.5s).

Exit any menu item by pressing the MENU button longer than >1s.

Exit setup mode:

Exit the setup mode by moving the slide switch to position "AUTO" and confirming the notification message.

Alternatively press the MENU button in the top menu layer longer than >1s and confirm the notification message. The actuator then changes to manual mode (MANU mode).



A warning message is displayed when switching between different operating modes, because the actuator can run under certain conditions. Confirm the message with the MENU button.



The actuator may run and move the connected valve when switching from MANU to AUTO and you confirm the warning message.

After switching from MANU to AUTO and confirming the warning message the actuator can be operated by using the buttons "L" & "R".

6.1.3 Menu system overview

Menu items

Depending on the selected user, stored access authorisation, set parameters and the model type of the actuator, single menu items may be invisible/hidden differing from the following overview.

x = menu item visible

Menu	Sub item	Function	Standard	POTI (Potentiometer)	A-OUT (Analog output, Current/Voltage output	CONTROL (Controller, i-Act)
MAIN MENU		Main Menu		*		
	LOGIN	Login (Select user)			X	
	End positions	Set up end positions (Left & right)				
	Poti input	Settings for operating the actuator via external potentiometer				χ
	Poti output	Settings for potentiometer output values (Feedback)		Х		χ
	Set value	Settings for set value defaults (Drive via set value)				χ
	Actual value	Settings for actual value output (Feedback current/voltage)			Х	χ
	Relay switch	Programming relays behaviour (Option board)	visible or		ached relay: ı board)	s module
EXPT. MENU		Expert Menu				
	Signal IN	Selection of input signal for driving the actuator		2	(
	Signal OUT	Selection of output signal for position feedback				
	Wire monitor	Setting of actuator behaviour in case of cable breakage (formerly wire break monitoring)				χ
	Status info	Activate/Deactivate message output		χ	χ	χ
	Offset	Settings for allowed control deviation in controller mode				χ

	Hyst. Start	Define start hysteresis	
	Hyst. Stop	Define stop hysteresis	
	Stall-det.	Settings for block detection	
	Block-det.	Settings for block detection near the end positions	χ
	RPM acc.	Define acceleration ramp of actuator	
	RPM red.	Define break ramp of actuator	
	Add feature	Entry of activation code for function extensions	
POWR. MENU		Power Menu	
	Torque/Speed	Selection of a torque/time combination for CCW resp. CW rotation	Х
INFO MENU		Information Menu	
	Firmware	Indicates firmware revision	
	Hardware	Indicates hardware revision	
	Serial-No.	Indicates serial number of the electronics	v
	Features	Indicates unlocked actuator functions	Х
	On-time	Indicates operating hours of the actuator	
	Cycl. Count	Indicates number of starts of the actuator	
	Modules	Indicates connected modules/option boards	

Menu items in detail

MAIN MENU

Login	Enables selection of an access level. If a password has been stored, enter it here to proceed to further menu items. Depending on the selected access level, single menu items may not be visible or adjustable. If the login is missing, only the INFO MENU and the menu item LOGIN (in MAIN MENU) are visible.
	The following users are selectable: User
	 Service Manufacturer (ARIS only)
	A logged in user can be logged out via the menu item "Logout".

Login (Contd.)	! ADVICE
	A user has to be selected/logged in on initial switch on or after a voltage loss, even if no password was given for the
	selected user. If no password was stored for the user, the password entry is skipped and the first menu item will be displayed.
	Password entry: Select the appropriate figure via buttons L & R (actual figure is flashing) To edit the figure press the MENU button -> An underscore is shown below the figure. Set selected figure by using buttons L & R. Confirm the set figure with the MENU button. Navigate to the confirmation arrow after password entry and confirm with the MENU button.
	No error message is shown when entering a wrong password. A correct password or the active user is marked with an asterisk (*) behind the selected user. Example with user "User": Password correct/User active: > User* Password wrong/User inactive: > User
End positions	End positions
	Selection and setting of the left (EL) and right (ER) end position.
	Approach end positions using buttons L and R and then store them.
	Procedure: Select the end position to be set Within the display " <el>" or "<er>" approach left resp. right end position via buttons L & R and confirm with MENU button Accept (Y) or cancel (N) storing the end positions. Change between (Y)/(N) via buttons L & R, confirm selection with MENU button.</er></el>
	Motor or parts can be damaged when driving against obstacles. The motor does not stop at the prior set end positions during an end position is re-programmed. Drive the actuator slowly and carefully when setting new end positions.
	Left and right end positions can be interchanged. The assignment of the turning direction of the inputs 2/3 and the buttons LI/RE do not change.
	The end positions must be 28° apart due to technical reasons. If the difference range is too small, the actuator will prompt "Error Code 51".

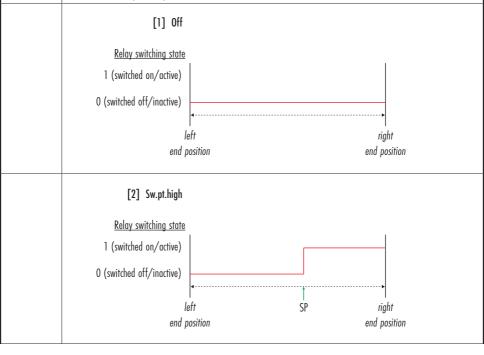
Poti Input	Actuator control via external potentiometer, only visible and adjustable with "Signal IN" = "Poti"
	Matching of the set value signal for the left and right end positions for controlling the actuator via a potentiometer. This menu item can only be set, when "Poti" is selected under "Signal IN". The DIP switch must be set correctly on the board (see menu item "Signal IN"). The connected potentiometer is supplied with 5 V DC via the electronics of the actuator. The set value signal of both end positions can be set as a percentage of the total voltage applied to the potentiometer. The following settings are possible for the left and right end positions: Set value signal = 0% 10% 90% 100% free (free values, selectable via display)
Poti Output	Position feedback via potentiometer, only visible and adjustable with "Signal OUT" = "Poti"
	Setting of the actual value signal at the output of the electrical potentiometers relating to the left and right end position. This menu item can only be set, when "Poti" is selected under "Signal OUT". The DIP switch must be set correctly on the board (see menu item "Signal OUT"). The actual value signal of both end positions can be set as a percentage of the total voltage applied to the potentiometer. The following settings are possible for the left and right end positions: $Actual \ value \ signal = 0\% \ \ 10\% \ \ 90\% \ \ 100\% \ \ free \ (free \ values, \ selectable \ via \ display)$
	The terminal designation for the potentiometer output is differently to prior Tensor electronics. The original terminals 18 and 19 are replaced with terminals 54 and 55. Wiring diagram see description for "Signal OUT".
	Performance data for potentiometer Resolution: 12 bit Output impedance: 1 k Ω Supply voltage: 4.7528.8 V DC
Set Value	Settings for set value input when controlling with i-Act controller, only adjustable with "Signal IN" = "Ctrl. [mA]" or "Ctrl. [V]"
	Matching the set value signal for the left and right end position. This menu item can only be set, when "Ctrl. [mA]" or "Ctrl. [V]" is selected under "Signal IN". The set value signal of both end positions can be set as follows: Set value signal current = 0 mA 4 mA 20 mA free (free values, selectable via display) Set value signal voltage = 0 V 2 V 10 V free (free values, selectable via display)
	For a proper function, the DIP switch near the buttons must be set equivalent to the settings in the menu! Setting the DIP switch see description for "Signal IN". NOTICE: Defaults for the set value of the end positions must cover min. 20% of the total range, otherwise "Error Code 80" will be displayed. Example: Signal range 4 mA => Coverage 4 mA x 20% = 0.8 mA Lower end position 0.1 mA => Upper end position min. 0.9 mA (= 0.1 mA + 0.8 mA)

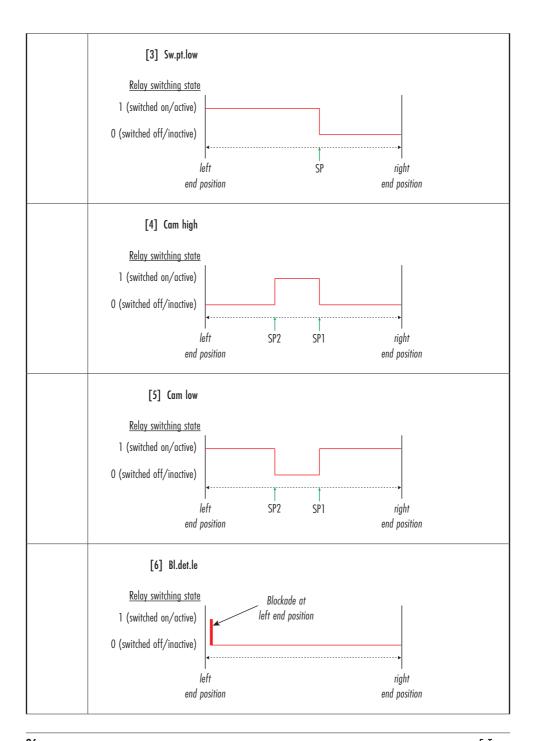
Set Value (Contd.)	$\begin{tabular}{ll} \hline Performance data for set value input \\ Resolution: 12 bit \\ Set value input: Current input 020 mA, Burden 50 \Omega \\ Voltage input 010 \ V \ DC, input impedance > 200 \ k\Omega \\ \hline \end{tabular}$
Actual Value	Settings for actual value output as position feedback, only adjustable with "Signal OUT" = "Ctrl. [mA]" or "Ctrl. [V]"
	Matching the actual value signal for the left and right end position. This menu item can only be set, when "Ctrl. [mA]" or "Ctrl. [V]" is selected under "Signal OUT". The actual value signal of both end positions can be set as follows: Set value signal current = 0mA 4 mA 20 mA free (free values, selectable via display) Set value signal voltage = 0 V 2 V 10 V free (free values, selectable via display)
	For a proper function, the DIP switch near the buttons must be set equivalent to the settings in the menu! Setting the DIP switch see description for "Signal OUT". NOTICE: Defaults for the set value of the end positions must cover min. 20% of the total range, otherwise "Error Code 70" will be displayed.
	Performance data for actual value output Resolution: 12 bit Actual value encoder: Magnetic position sensor Actual value output: Current output 020 mA, Burden 50 Ω Voltage output 010 V DC
Relay Switch	Relay settings for options board with additional switches for position feedback, only adjustable in combination with mounted relay board
	Behaviour setup for the bi-stable relays on the relay board. Up to 4 relays are available, depending on the chosen relay board. The switching state of the relays is retained even in currentless condition, so that the auxiliary switches can be used.
	Performance data of relay (Add-on board) Amount of relays: 2 (optional 4) Relays type: Bi-stable relay Switching voltage: max. 250 V AC / 125 V DC Allowed continuous current/channel: max. 2 A (at 230 V AC / 30 V DC); max. 0.2 A (at 125 V DC)

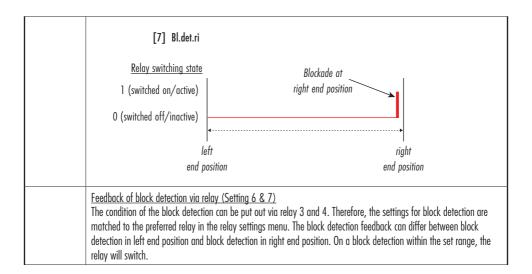
Relay Switch (Contd.)

The following relay settings are available:

- 1. "Off": Relays switched off/inactive
- "Sw.pt.high" (Switch point high): Relay is switched on/active from right end position to the set switching point SP. Relay is switched off/inactive from left end position to the set switching point SP.
- "Sw.pt.low" (Switch point low): Relay is switched off/inactive from right end position to the set switching point SP. Relay is switched on/active from left end position to the set switching point SP.
- 4. "Cam high" (Switch cam high): Relay is switched off/inactive from right end position to the set switching point SP1, switched on/active between switching points SP1 and SP2 and switched off/inactive again after switching point SP2. Relay is switched off/inactive from left end position to the set switching point SP2, switched on/active between switching points SP2 and SP1 and switched off/inactive again after switching point SP1.
- 5. "Cam low" (Switch cam low): Relay is switched on/active from right end position to the set switching point SP1, switched off/inactive between switching points SP1 and SP2 and switched on/active again after switching point SP2. Relay is switched on/active from left end position to the set switching point SP2, switched off/inactive between switching points SP2 and SP1 and switched on/active again after switching point SP1.
- "Bl.det.le" (Block detection left): Relay switches off when detecting a blockage in range of the left end position. Settable only on relays no. 3 & 4!
- "Bl.det.ri" (Block detection right): Relay switches off when detecting a blockage in range of the right end position.
 Settable only on relays no. 3 & 4!

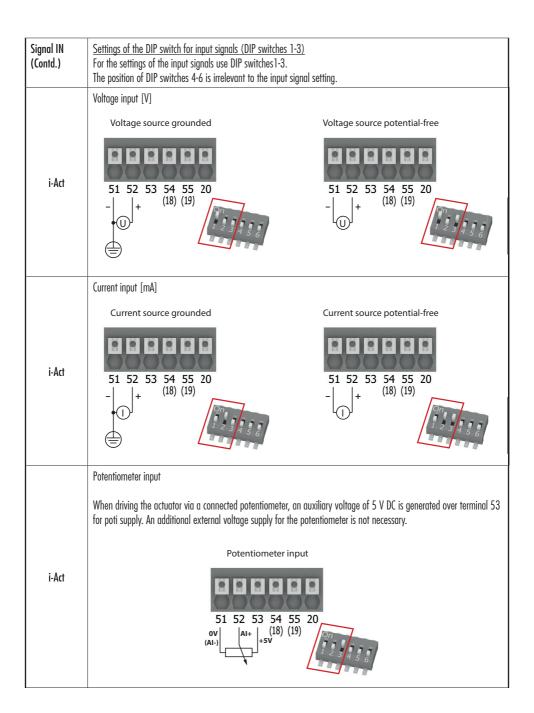






EXPT. MENU (Expert menu)

Signal IN	Input signal
	Selection of input signal type for controlling the actuator.
	The following control features are available (depending on the activated features):
	 Term. 2/3 (Terminal 2/3): Driving the actuator via terminal 2/3. Ctrl. [mA] (Control [mA], i-Act): Driving the actuator by feeding a set value signal in range 020 mA. Ctrl. [V] (Control [V], i-Act): Driving the actuator by feeding a set value signal in range 010 V. Poti (Potentiometer, i-Act): Driving the actuator via a connected external potentiometer.
	Property is a property of the desired signal type. The input signal type must additionally be set up with the onboard DIP switch, according to the desired signal type.
	DIP switch 1 and DIP switch 2 must not be active (On) simultaneous! DIP switch 4 and DIP switch 5 must not be active (On) simultaneous!



Signal OUT	Output signal	
	Selection of the output signal type, used as position feed The following position feedbacks are available (depending	
	Feedback signal: Off: No feedback of actuator position. Ctrl. [mA] (Control [mA], i-Act or current/voltage ou Ctrl. [V] (Control [V], i-Act or current/voltage output Poti (Potentiometer): Output of a voltage value of the actuator position.	
	The input signal type must additionally be set up with the DIP switch 1 and DIP switch 2 must not be active (On) sid DIP switch 4 and DIP switch 5 must not be active (On) sides.	
	Settings of the DIP switch for output signals (DIP switche For the settings of the output signals use DIP switches 4- The position of DIP switches 1-3 is irrelevant to the output	5.
	Voltage output [V]	Current output [mA]
i-Act Current/Voltage output	Voltage output 51 52 53 54 55 20 (18) (19)	51 52 53 54 55 20 (18) (19)
Potentiometer electronical	Potentiometer output Voltage source grounded 51 52 53 54 55 20 (18) (19) U- U- U- 5-24V	Potentiometer output Voltage source potential-free 51 52 53 54 55 20 (18) (19) U- + U+ U+ U+ U+ U+ U+ U

Signal OUT (Contd.)	() ADVICE		
		the potentiometer output is different to prior Tensor electronics. The original terminal e substituted by 54 and 55 (see wiring diagram).	
Wire Monitor	Wire monitoring, formerl	y wire break monitoring	
	The monitoring works only	signal at the terminals when driving the actuator with set value signals (mA resp. V). with preset values $4\dots20$ mA resp. $2\dots10$ V. g mA resp. <1 V is detected as an error and the error code 90 is displayed.	
	The following actuator beha	aviour can be set:	
	Setting	Behaviour on missing/wrong set value signal	
	Off	Monitoring deactivated	
	Stop	Actuator stops	
	Open	Actuator moves to OPEN position (turning direction of shaft CCW)	
	Close	Actuator moves to CLOSE position (turning direction of shaft CW)	
	Position	Actuator moves to a preset position	
	value signal. Confirm desired position with the MENU button. Confirm (Y) or cancel (N) storing the position. Change between (Y)/(N) via buttons L & R, confirm selection with the MENU button.		
Status Info	Message output		
	The message output delivers the actual status of the actuator via a potential-free contact. The following settings are possible: Off: Message output not active (no feedback over terminal 56 57) On: Message output active		
		-	
	Performance data of the m Switching voltage: 250 V A Allowed continuous current	AC / 30 V DC	

Offset	Control variance
	Setting of the max. variance allowed between actual and set value of the controller (Standard variance). The allowed variance is stated in % depending on the set travel of the actuator. An override of the set max. variance will indicate an error at the message output (see "Status Info").
	Possible settings: 0 = Standard variance check deactivated 19% = Allowed standard variance in %
	Example: Menu setting = 2% Right end position 0% [0°] / Left end position 100% [90°]. A 90° travel corresponds to a max. allowed variance of 90° x 2% = 1.8° . The message output opens on a variance of the actual position from the set position of $>1.8^\circ$.
Hyst. stop	Shut-off hysteresis
	The shut-off hysteresis defines the shut-off accuracy of the actuator when reaching the default set value position. The actual position of the actuator is checked against the set position and the default hysteresis value. The actuator stops if the actual position lies within the (shut-off) hysteresis range around the set value.
	The shut-off hysteresis of the actuator in control mode can be set in steps of 0.01% in a range of 05.00%.
	(!) ADVICE
	The shut-off hysteresis has to be set lower than the turn-on hysteresis!
	If the hysteresis is set too low, the actuator may operate in an unwanted behaviour depending on the actuator type. In this case, the hysteresis must be increased.
Hyst. start	Turn-on hysteresis
	The turn-on hysteresis defines at which variance from the actual position to the set position the actuator will readjust. The actual position of the actuator is checked against the set position and the default hysteresis value. If the actual position of the actuator lies outside the (tun-on) hysteresis range around the set position, the actuator moves to the deafult set position.
	The turn-on hysteresis of the actuator in control mode can be set in steps of 0.01% in a range of 05.00% .
	(!) ADVICE
	The turn-on hysteresis has to be set higher than the shut-off hysteresis!
	If the hysteresis is set too low, the actuator may operate in an unwanted behaviour depending on the actuator type. In this case, the hysteresis must be increased.

Stall-Det.	Stall detection
	The stall detection recognizes an accidental halt of the actuator and the BLDC motor, caused by a blockade. Subsequently the actuator stops to avoid damages to the actuator or the connected valve and an error code (Error Code 3X) is displayed.
	The error can be reset by driving the actuator in the opposite direction.
Block-Det.	Block detection in range of the end positions
	The block detection recognizes the run of the actuator against an intended block (e.g. valve seal, valve stop bar, etc.) within a settable range around the end positions and suppresses a stall error in this range.
	The capture range of the block detection is set in % from the right resp. left end position and can be set differently for both end positions.
	The following settings are possible: 0 = Block detection deactivated 110% = Capture range of block detection at an end position
	The block detection condition can be put out via the relays 3 and/or 4 (if applicable). See further information in section "Relay switch".
	If a block was detected, it will be interpreted as an end position. The display of the actuator's position (in %) stays uneffected from the block detection. On a block detection, reset the detection by driving the actuator in the opposite direction. The actuator turns off, if it reaches a default end position.
	Example: Menu setting: Block detection left/right = 2% When the actuator reaches the actual position <2% resp. >98% and detects a blockade in this range, the actuator stops on the blockade position. Relay 3 or 4 reacts depending on the equipment and setting of the actuator. No error will be displayed.
RPM acc.	Acceleration ramp
	Defines the time [ms] of the acceleration ramp of the actuator in AUTO mode.
RPM red.	Brake ramp
	Defines the time [ms] of the brake ramp of the actuator in AUTO mode.

Add feature	Adding features
	Enables the entry of an access code for activation of further actuator features. The following features can be activated by entering the access code: Potentiometer: Activation of the electronical potentiometer for position feedback Current/Voltage output: Activation of the current/voltage output for position feedback i-Act: Activation of the electronical potentiometer, the current/voltage output for position feedback and activation of the potentiometer input and the current/voltage input for controlling the actuator via set value signals ([mA] & [V]).
	If you are interested in any additional feature, please contact the ARIS sales department and have the serial number of the mounted electronics ready (check INFO MENU "Serial-No.").

POWR. MENU (Power menu)

Torque/Speed	Torque/Actuating speed	
	Enables the setting of pre-defined torque/time combinations. The setting of the torque/time combination can be made separately and differently for both turning directions "CCW" and "CW".	

INFO MENU (Information menu)

Firmware	Displays the firmware version of the electronics.	
Hardware	Displays the version of the electronics hardware.	
Serial-No.	Serial number	
	Displays the serial number of the actuator's electronics. The serial number of the electronics is used for the activation of additional actuator features and may be asked by the ARIS customer service.	
Features	Functions/Features	
	Shows active features/functions and further available features/functions of the actuator.	
	The status of the different functions is marked as follows: Example for feature/function "POTI": Feature/Function activated: > POTI*	

On-time	Operating hours counter
	Displays the overall operating hours of the actuator.
	The operating hours counter starts as soon as the actuator is supplied with power and stops when the power supply is cut off. The operating hours are stored even when a power failure occurs. A reset of the operating hours is not possible.
Cycl. count	Cycle count
	The cycle count counts the number of starts of the actuator in AUTO mode. The number of starts is stored even in case of a voltage cutoff. A reset of the counter is not possible.
Modules	Modules
	Displays (add-on) boards which are connected with the electronics. Connected and recognized boards are marked with an asterisk (*) after the board name.
	Example with relay board: Board connected/recognized: > Relay* Board not connected/not recognized: > Relay
	! ADVICE
	Add-on boards must only be mounted/dismounted when the electronics is de-energized!

6.1.4 Handwheel

If the actuator is equipped with the "handwheel" option, it can be moved using the external handwheel when the power is off. To do this, press in the handwheel and then turn it by hand. When doing this, turn with particular care in the areas of the end positions of fittings, since high torques can be transmitted through the handwheel.

After the adjustment, the handwheel automatically disengages and jumps back to its original position. The handwheel does not turn during normal operation of the actuator.



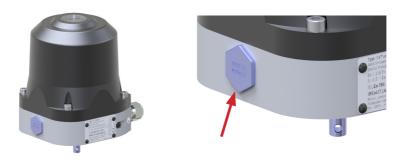
Turning is only permitted by hand.

The handwheel may only be used when the drive is de-energized (no voltage/no current).



WARNING

Danger! On the back of the drive, there is a blind plug to close the handwheel option for equipment variants without a handwheel. This may not be removed or altered.



7. Options

more options - mechanichal poti, terminals ...?

8. Maintenance and service

ARIS actuators of the ExTensor series have permanent lubrication and are basically maintenance-free. We recommend carrying out a function test and a visual inspection once a year.

Repairs: No repairs or mechanical processing of any kind may be carried out on the gap surfaces of the flameproof gaps. In particular, the cover/housing gap surfaces must not be changed.



Non-observance can lead to serious accidents and damage to property - The ATEX/IECEX Approval for the device expires in the event of non-compliance or misuse.

Cleaning

Only clean the actuator with a damp cloth. Never clean with a high-pressure cleaner.



- Pressure proof encapsulation
- Before opening, ensure that there is no gas and no voltage
- Joint surfaces must not show any damage or contamination
- The hood must not tilt during assembly



Regular maintenance work:

- The type and scope of the tests correspond to the relevant national regulations (e.g. IEC/EN 60079-17).
- The deadlines are calculated in such a way that any defects that are to be expected be identified in a timely manner.

9. Declaration of incorporation



Declaration of Incorporation of partly completed machinery

according
EU directive 2006/42/EC Annex II B "Machinery Directive"

Herewith we declare, that the below mentioned incomplete machinery

Product description:		Electrical actuator
Pr	roduct Types:	ExTensor and identical

fulfills the basic requirements of the annex I of the directice 2006/42/EC, if it applies to the appropriate order:

1.1.2c,e; 1.1.3; 1.1.5; 1.3.4; 1.5.1; 1.5.2; 1.5.4; 1.5.5; 1.5.6; 1.5.8; 1.5.9; 1.5.11; 1.6.1; 1.6.4; 1.7.3; 1.7.4

The product has been designed in accordance with the directives of the European Union. Its conformity with the following standards and directives is ensured:

- DIN EN ISO 12100:2011-03 ("Safety of machinery")
- 2014/35/EU (Low Voltage Directive)
- 2014/30/EU (Electromagnetic Compatibility / EMC Directive)
- 2011/65/EU (Restriction of the Use of Certain Hazardous Substances.../ RoHS Directive).

The product is a partly completed machinery in accordance with Article 2 letter g of the Directive 2006/42/EG. The special technical documents according to annex VII part B have been created. On reasonable requests these documents can be sent electronically to the responsible authorities.

The initial operation of this incomplete machinery is only permitted, if it is approved that the facility or machinery in which it will be installed corresponds to the european directive 2006/42/EC, if it applies.

Authorized representative for collection of relevant technical documents:

Raimund Schulte Quality and product safety ARIS Stellantriebe GmbH Rotter Viehtrift 9 D-53842 Troisdorf

This declaration is invalid if the machinery is changed or rebuilt in a manner it was not designed for.

Troisdorf, 03.05.2023

R. Schulte (Quality and product safety)

ARIS Stellantriebe GmbH www.stellantriebe.de Rotter Viehtrift 9 D-53842 Troisdorf Telefon +49(0)2241-25186-0 Telefax +49(0)2241-25186-99

10. Declaration of Conformity



EC - Declaration of Conformity

Herewith we declare

Name:	ARIS Stellantriebe GmbH
Adress:	Rotter Viehtrift 9, D - 53842 Troisdorf

in sole responsibility that the product

Designation:	Electric actuator
Series:	ExTensor and identical

to which this declaration refers, complies with the essential requirements of the following European directives by being in accordance with the specified harmonized standards:

Dir 2014/34/EU (ATEX)

DIN EN IEC 60079-0:2019

DIN EN 60079-1:2015 (IEC 60079-1:2014, Ed. 7.0)

DIN EN 60079-31:2014 (IEC 60079-31:2013, Ed. 2.0)

DIN EN ISO/IEC 80079-34:2020-06

The actuators mentioned are group II and III devices in the sense of DIN EN IEC 60079-0 and comply with the therein specified device protection levels

Gb, Group II, Subgroup IIC as well as Db, Group III, Subgroup IIIC

In accordance with Directive 2014/34/EU, they meet the explosion protection requirements for Group II equipment and the following categories

2G in type of protection flameproof enclosure "db" for use in zone 1

2D in type of protection dust explosion protection by enclosure "tb" for use in zone 21

The explosion protection marking for the actuators of this series is as follows

II 2G Ex db IIC T6 Gb

€ II 2D Ex tb IIIC T80 °C Db

Ta -20 °C ... +60 °C

The conformity assessment with regard to Dir 2014/34/EU has been confirmed by the type examination report ${\bf IBExU22ATEX1066X}$ / ${\bf 0}$.

DIN EN IEC 63000:2019-05

DIN EN IEC 61000-6-1:2019-11 / ...-2:2019-11 / ...-4:2020-09

The technical documentation has been fully created.

This declaration becomes invalid if the actuator is modified in any way that has not been approved by us or if the actuator is not used for the intended purpose.

Troisdorf 03.05.2023

i.V. R. Schulte (Quality and product safety)

ARIS Stellantriebe GmbH www.stellantriebe.de Rotter Viehtrift 9 D-53842 Troisdorf Telefon +49(0)2241-25186-0 Telefax +49(0)2241-25186-99

11. Type examination certificate

IBExU Institut für Sicherheitstechnik GmbH

An-Institut der TU Bergakademie Freiberg

EU-TYPE EXAMINATION CERTIFICATE - TRANSLATION [1]

[2] Equipment and protective systems intended for use in potentially explosive atmospheres, directive 2014/34/EU



EU-Type Examination Certificate Number IBExU22ATEX1066 X | Issue 0 [3]

[4] Equipment: Actuator Type: ExTensor

Manufacturer:

[5]

ARIS Stellantriebe GmbH

[6] Address: Rotter Viehtrift 9 53842 Troisdorf GERMANY

This product and any acceptable variation thereto are specified in the schedule to this certificate and [7] the documents therein referred to.

[8] IBExU Institut für Sicherheitstechnik GmbH, Notified Body number 0637 in accordance with Article 17 of Directive 2014/34/EU of the European Parliament and of the Council, dated 26 February 2014, certifies that this product has been found to comply with the essential health and safety requirements relating to the design and construction of products intended for use in potentially explosive atmospheres given in Annex II to the Directive.

The examination and test results are recorded in the confidential test report IB-21-3-0033.

Compliance with the essential health and safety requirements has been assured by compliance with: [9]

EN IEC 60079-0:2018

EN 60079-1:2014

EN 60079-31:2014

Except in respect of those requirements listed at item [18] of the schedule.

[10] If the sign "X" is placed after the certificate number, it indicates that the product is subject to the specific conditions of use specified in the schedule to this certificate.

- [11] This EU-type examination certificate relates only to the design and construction of the specified product. Further requirements of the Directive apply to the manufacturing process and supply of this product. These are not covered by this certificate.
- [12] The marking of the product shall include the following:

(II 2G Ex db IIC T6 Gb

(II 2D Ex th IIIC T80 °C Db

Ta -20 °C ... +60 °C

IBExU Institut für Sicherheitstechnik GmbH

Fuchsmühlenweg 7 09599 Freiberg, GERMANY

By order

Dr.-Ing. P. Cimalla

The Exp BEXU Institut für Sicherheitstechnik Seal -

(Notified Body number 0637)

Phone: +49 (0)3731 3805-0 Fax: +49 (0)3731 3805-10

Certificates without seal and signature are not valid. Certificates may only be duplicated completely and unchanged. In case of dispute, the German text shall prevail

Freiberg, 2023-03-21

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IBExU Institut für Sicherheitstechnik GmbH

An-Institut der TU Bergakademie Freiberg

[13] Schedule

[14] Certificate number IBExU22ATEX1066 X | Issue 0

[15] Description of product

The Actuator type ExTensor is a high-precision, multi-turn, electronically controlled actuator with contactless, wear-free position detection. It consists of a flameproof enclosure with shaft feed-through and direct cable entry. For group IIIC, dust explosion protection is ensured by the type of protection "tb".

Technical data

- Power input: max. 60 VA

- Supply voltage: 85...265 V AC, 24 V DC (±10 %)

Torque: max. 40 Nm Run time for 90° 0.7...500 s

Ambient temperature range: -20 °C up to +60 °C
 IP-Degree of protection according to EN 60529: IP65/67

- Property class fastening screws: min. A2-70
- Temperature limiter: +85 °C

[16] Test report

The test results are recorded in the confidential test report IB-21-3-0033 of 2023-03-14. The test documents are part of the test report and they are listed there.

Summary of the test results

The Actuator type ExTensor fulfils the requirements of explosion protection for equipment of Group II, Category 2G, type of protection flameproof enclosure "db" and Category 2D, type of protection dust ignition protection by enclosure "tb".

[17] Special conditions for use

- Repairs of the flameproof joints must be made in compliance with the constructive specifications provided by the manufacturer. Repairs must not be made on the basis of values specified in tables 2 and 3 of EN 60079-1.
- Only the fastening screws specified by the manufacturer (strength class min. A2-70) according to ISO 4762 may be used.
- The used cable glands must be suitable for a max. operating temperature of at least 80 °C. Unused openings for cable entries must be durably closed with suitable blanking elements certified for explosion protection according to EN 60079-1 for group IIC or EN 60079-31 for group IIIC.

[18] Essential Health and Safety Requirements

In addition to the essential health and safety requirements (EHSRs) covered by the standards listed at item [9], the following are considered relevant to this product, and conformity is demonstrated in the test report:

- not applicable -

[19] Drawings and documents

The documents are listed in the test report.

IBExU Institut für Sicherheitstechnik GmbH

Fuchsmühlenweg 7

09599 Freiberg, GERMANY

Dr.-Ing. P. Cimalla

Freiberg, 2023-03-14

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By order

Subject to technical changes.

ARIS Stellantriebe GmbH Rotter Viehtrift 9 53842 Troisdorf / Germany Tel.: +49 2241 25186-0 Fax: +49 2241 25186-99 aris@stellantriebe.de

